

Geometrical methods in loop calculations and the three-point function

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A geometrical way to calculate N -point Feynman diagrams is reviewed. As an example, the dimensionally-regulated three-point function is considered, including all orders of its ε -expansion. Analytical continuation to other regions of the kinematical variables is discussed.

1. INTRODUCTION

The analytical structure of the results for N -point Feynman diagrams can be better understood if one employs a geometrical interpretation of kinematic invariants and other quantities. For example, the singularities of the general three-point function can be described pictorially through a tetrahedron constructed out of the external momenta and internal masses (see Fig. 1a). This method can be used to derive Landau equations defining the positions of possible singularities [1] (see also in [2]).

In Ref. [3] it was demonstrated how such geometrical ideas could be used for an analytical calculation of one-loop N -point diagrams. For example, in the three-point case in n dimensions, the result can be expressed in terms of an integral over a spherical (or hyperbolic) triangle, as shown in Fig. 1b, with a weight function $\cos^{3-n} \theta$, where θ is the angular distance between the integration point and the point 0, corresponding to the height of the basic tetrahedron (see in [3]). This weight function equals 1 for $n = 3$ (see also in [4]). For $n = 4$, one can get another representation [5,6], in terms of an integral over the volume of an asymptotic hyperbolic tetrahedron. Here we will discuss the application of the approach of Refs. [3,7] to the three-point function in any dimension n , as well as its ε -expansion ($n = 4 - 2\varepsilon$) within dimensional regularization [8].

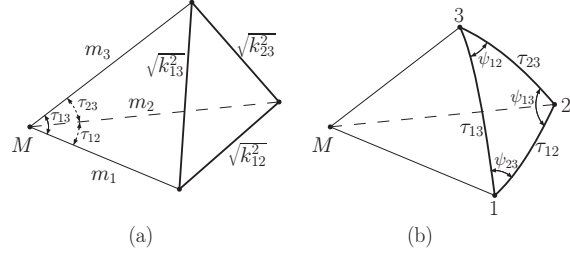


Figure 1. Three-point case: (a) the basic tetrahedron and (b) the solid angle

2. TRIGONOMETRIC STUFF

We will use notations defined in [3], namely:

$$c_{jl} = \cos \tau_{jl} \equiv \frac{m_j^2 + m_l^2 - k_{jl}^2}{2m_j m_l}, \quad (1)$$

$$\cos \tau_{0i} = \frac{m_0}{m_i}, \quad m_0 = m_1 m_2 m_3 \sqrt{\frac{D^{(3)}}{\Lambda^{(3)}}}, \quad (2)$$

$$\begin{aligned} \Lambda^{(3)} &= -\frac{1}{4} [(k_{12}^2)^2 + (k_{13}^2)^2 + (k_{23}^2)^2 \\ &\quad - 2k_{12}^2 k_{13}^2 - 2k_{12}^2 k_{23}^2 - 2k_{13}^2 k_{23}^2] \\ &= -\frac{1}{4} \lambda(k_{12}^2, k_{13}^2, k_{23}^2), \end{aligned} \quad (3)$$

$$\begin{aligned} D^{(3)} &\equiv \begin{vmatrix} 1 & c_{12} & c_{13} \\ c_{12} & 1 & c_{23} \\ c_{13} & c_{23} & 1 \end{vmatrix} \\ &= 1 - c_{12}^2 - c_{13}^2 - c_{23}^2 + 2c_{12}c_{13}c_{23}. \end{aligned} \quad (4)$$

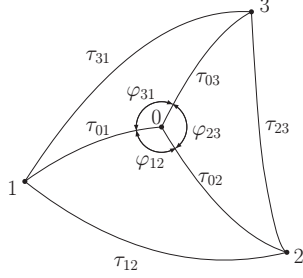


Figure 2. The spherical triangle 123

Assuming that all $|c_{jl}| \leq 1$, $\Lambda^{(3)} > 0$, and $D^{(3)} > 0$, we get spherical triangles. In other cases, we need to use the hyperbolic space. The transition corresponds to the analytic continuation (see below).

Using the approach of Ref. [3], we split the spherical triangle into three smaller ones (see Fig. 2), so that $\varphi_{12} + \varphi_{23} + \varphi_{31} = 2\pi$. Moreover, it is convenient to split each of the resulting triangles into two rectangular ones, as shown in Fig. 3. By definition, $\frac{1}{2}(\varphi_{12}^+ + \varphi_{12}^-) = \varphi_{12}$, $\frac{1}{2}(\tau_{12}^+ + \tau_{12}^-) = \tau_{12}$. Let us list useful relations between the sides and angles of the spherical triangle (see also in [3]):

$$\cos\left(\frac{1}{2}\tau_{12}^+\right) = \frac{\cos\tau_{01}}{\cos\eta_{12}},$$

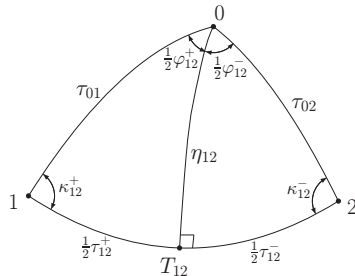


Figure 3. An asymmetric spherical triangle 012

$$\begin{aligned} \cos\left(\frac{1}{2}\tau_{12}^-\right) &= \frac{\cos\tau_{02}}{\cos\eta_{12}}, \\ \cos\left(\frac{1}{2}\varphi_{12}^+\right) &= \frac{\tan\eta_{12}}{\tan\tau_{01}}, \\ \cos\left(\frac{1}{2}\varphi_{12}^-\right) &= \frac{\tan\eta_{12}}{\tan\tau_{02}}, \\ \sin\left(\frac{1}{2}\tau_{12}^+\right) &= \sin\tau_{01} \sin\left(\frac{1}{2}\varphi_{12}^+\right), \\ \sin\left(\frac{1}{2}\tau_{12}^-\right) &= \sin\tau_{02} \sin\left(\frac{1}{2}\varphi_{12}^-\right), \\ \tan\left(\frac{1}{2}\tau_{12}^\pm\right) &= \sin\eta_{12} \tan\left(\frac{1}{2}\varphi_{12}^\pm\right), \\ \sin\eta_{12} &= \sin\tau_{01} \sin\kappa_{12}^+ = \sin\tau_{02} \sin\kappa_{12}^-, \\ \cos\kappa_{12}^\pm &= \cos\eta_{12} \sin\left(\frac{1}{2}\varphi_{12}^\pm\right). \end{aligned}$$

Worth noting is

$$\cos\eta_{12} = \frac{m_0 \sqrt{k_{12}^2}}{m_1 m_2 \sin\tau_{12}}. \quad (5)$$

Therefore,

$$\begin{aligned} \cos\left(\frac{1}{2}\tau_{12}^+\right) &= \frac{m_2 \sin\tau_{12}}{\sqrt{k_{12}^2}}, \\ \sin\left(\frac{1}{2}\tau_{12}^+\right) &= \frac{m_1^2 - m_2^2 + k_{12}^2}{2m_1 \sqrt{k_{12}^2}}, \\ \cos\left(\frac{1}{2}\tau_{12}^-\right) &= \frac{m_1 \sin\tau_{12}}{\sqrt{k_{12}^2}}, \\ \sin\left(\frac{1}{2}\tau_{12}^-\right) &= \frac{m_2^2 - m_1^2 + k_{12}^2}{2m_2 \sqrt{k_{12}^2}}. \end{aligned}$$

In a triangle with the sides m_1 , m_2 and $\sqrt{k_{12}^2}$, the angles $\frac{1}{2}\tau_{12}^+$ and $\frac{1}{2}\tau_{12}^-$ are those between the height of the triangle and the sides m_1 and m_2 , respectively. Therefore, the point T_{12} in Fig. 3 corresponds to the intersection of this face height and the sphere.

3. HYPERGEOMETRIC STUFF

Eqs. (3.38)–(3.39) of [3] yield

$$J^{(3)}(n; 1, 1, 1) = -\frac{i\pi^{n/2}\Gamma\left(3 - \frac{n}{2}\right)}{m_0^{4-n}\sqrt{\Lambda^{(3)}}} \Omega^{(3;n)}, \quad (6)$$

where $\Omega^{(3;n)}$ is an integral over the solid angle $\Omega^{(3)}$ (corresponding to triangle 123 in Fig. 1b),

$$\Omega^{(3;n)} = \int_{\Omega^{(3)}} \frac{\sin^{n-2}\theta \, d\theta \, d\phi}{\cos^{n-3}\theta}. \quad (7)$$

According to Fig. 2 and Fig. 3, $\Omega^{(3;n)}$ can be presented as a sum of six contributions:

$$\begin{aligned}\Omega^{(3;n)} = & \omega\left(\frac{1}{2}\varphi_{12}^+, \eta_{12}\right) + \omega\left(\frac{1}{2}\varphi_{12}^-, \eta_{12}\right) \\ & + \omega\left(\frac{1}{2}\varphi_{23}^+, \eta_{23}\right) + \omega\left(\frac{1}{2}\varphi_{23}^-, \eta_{23}\right) \\ & + \omega\left(\frac{1}{2}\varphi_{31}^+, \eta_{31}\right) + \omega\left(\frac{1}{2}\varphi_{31}^-, \eta_{31}\right), \quad (8)\end{aligned}$$

with (see Refs. [9,10,11])

$$\omega\left(\frac{1}{2}\varphi, \eta\right) = \frac{1}{2\varepsilon} \int_0^{\varphi/2} d\phi \left[1 - \left(1 + \frac{\tan^2 \eta}{\cos^2 \phi} \right)^{-\varepsilon} \right], \quad (9)$$

where $\varepsilon = \frac{1}{2}(4-n)$. Defining $\tan \frac{\tau}{2} = \sin \eta \tan \frac{\varphi}{2}$, we can obtain another useful representation,

$$\begin{aligned}\int_0^{\varphi/2} d\phi \left(1 + \frac{\tan^2 \eta}{\cos^2 \phi} \right)^{-\varepsilon} \\ = \sin \eta \cos^{2\varepsilon} \eta \int_0^{\tau/2} \frac{d\psi \cos^{2\varepsilon} \psi}{1 - \cos^2 \eta \cos^2 \psi}. \quad (10)\end{aligned}$$

The remaining ϕ -integral in Eq. (9) can be calculated using a substitution $\phi = \arctan\left(\frac{\sqrt{u}}{\sin \eta}\right)$. The result can be presented in terms of Appell's hypergeometric function F_1 ,

$$\begin{aligned}\omega\left(\frac{1}{2}\varphi, \eta\right) = & \frac{1}{2\varepsilon} \left[\frac{\varphi}{2} - \tan \frac{\varphi}{2} \cos^{2\varepsilon} \eta \right. \\ & \left. \times F_1\left(\frac{1}{2}, 1, \varepsilon; \frac{3}{2} \middle| -\tan^2 \frac{\varphi}{2}, -\tan^2 \frac{\tau}{2}\right) \right]. \quad (11)\end{aligned}$$

Moreover, using the transformation formula

$$\begin{aligned}F_1(a, b, b'; c|x, y) = & (1-x)^{-b}(1-y)^{-b'} \\ & \times F_1\left(c-a, b, b'; c \middle| \frac{x}{x-1}, \frac{y}{y-1}\right),\end{aligned}$$

the result can be presented as

$$\begin{aligned}\omega\left(\frac{1}{2}\varphi, \eta\right) = & \frac{1}{2\varepsilon} \left[\frac{\varphi}{2} - \sin \frac{\varphi}{2} \cos \frac{\varphi}{2} \cos^{2\varepsilon} \tau_0 \right. \\ & \left. \times F_1\left(1, 1, \varepsilon; \frac{3}{2} \middle| \sin^2 \frac{\varphi}{2}, \sin^2 \frac{\tau}{2}\right) \right], \quad (12)\end{aligned}$$

with $\cos \tau_0 = \cos \eta \cos \frac{\tau}{2}$. Similar F_1 functions occurred in Refs. [12,13] (cf. also Ref. [14]).

An important formula (shift $\varepsilon \rightarrow 1 + \varepsilon$, or $n \rightarrow n-2$) reads:

$$\begin{aligned}F_1\left(1, 1, \varepsilon; \frac{3}{2} \middle| x, y\right) = & \frac{y}{x} {}_2F_1\left(1, 1 + \varepsilon; \frac{3}{2} \middle| y\right) \\ & + \left(1 - \frac{y}{x}\right) F_1\left(1, 1, 1 + \varepsilon; \frac{3}{2} \middle| x, y\right). \quad (13)\end{aligned}$$

It can be supplemented by a Kummer relation:

$$\begin{aligned}(1-2\varepsilon) {}_2F_1\left(1, \varepsilon; \frac{3}{2} \middle| y\right) \\ = 1 - 2\varepsilon(1-z) {}_2F_1\left(1, 1 + \varepsilon; \frac{3}{2} \middle| y\right). \quad (14)\end{aligned}$$

Each of the three triangles in Fig. 2 may be associated with a specific three-point function $J_i^{(3)}(n; 1, 1, 1)$. According to Eq. (3.45) of [3], the result of such splitting reads

$$\begin{aligned}J^{(3)}(n; 1, 1, 1) \\ = \frac{m_1^2 m_2^2 m_3^2}{\Lambda^{(3)}} \sum_{i=1}^3 \frac{F_i^{(3)}}{m_i^2} J_i^{(3)}(n; 1, 1, 1), \quad (15)\end{aligned}$$

where $F_i^{(3)} = \frac{\partial}{\partial m_i^2} (m_i^2 D^{(3)})$ (see also in Ref. [4]).

The geometrical meaning of $F_i^{(3)}$ was discussed in [3]. In particular,

$$m_2^2 m_3^2 F_1^{(3)} + m_1^2 m_3^2 F_2^{(3)} + m_1^2 m_2^2 F_3^{(3)} = \Lambda^{(3)}$$

means that the volume of the basic tetrahedron equals the sum of the volumes after splitting.

For each of the integrals $J_i^{(3)}$, only one two-point function appears in the reduction formulae. For instance, using Eqs. (12) and (13) we get

$$\begin{aligned}(n-2)\pi^{-1} J_3^{(3)}(n+2; 1, 1, 1) \\ = -2m_0^2 J_3^{(3)}(n; 1, 1, 1) - J^{(3)}(n; 1, 1, 0), \quad (16)\end{aligned}$$

and similarly for $J_1^{(3)}$ and $J_2^{(3)}$. This yields a geometrical way to derive the recursion in n : just take Eq. (15), shift $n \rightarrow n+2$ and substitute Eq. (16). The result is

$$\begin{aligned}J^{(3)}(n+2; 1, 1, 1) \\ = -\frac{\pi m_1^2 m_2^2 m_3^2}{(n-2)\Lambda^{(3)}} \left\{ 2D^{(3)} J_3^{(3)}(n; 1, 1, 1) \right. \\ + \frac{F_1^{(3)}}{m_1^2} J^{(3)}(n; 0, 1, 1) + \frac{F_2^{(3)}}{m_2^2} J^{(3)}(n; 1, 0, 1) \\ \left. + \frac{F_3^{(3)}}{m_3^2} J^{(3)}(n; 1, 1, 0) \right\}, \quad (17)\end{aligned}$$

in agreement with Refs. [15,13] (see also [16,17]).

4. SPECIAL VALUES OF n

4.1. $n = 3$ ($\varepsilon = \frac{1}{2}$)

In this case, we can use the known reduction formula for the F_1 function,

$$F_1(a, b, b'; b+b' \middle| x, y)$$

$$= (1-y)^{-a} {}_2F_1 \left(a, b; b+b' \middle| \frac{x-y}{1-y} \right). \quad (18)$$

Taking into account that

$${}_2F_1 \left(1, 1; \frac{3}{2} \middle| z \right) = \frac{\arcsin \sqrt{z}}{\sqrt{z(1-z)}},$$

we get

$$F_1 \left(1, 1, \frac{1}{2}; \frac{3}{2} \middle| \sin^2 \frac{\varphi}{2}, \sin^2 \frac{\tau}{2} \right) = \frac{\pi - 2\kappa}{\sin \varphi \cos \tau_0},$$

with $\cos \kappa = \sin \frac{\varphi}{2} \cos \eta$ and $\cos \tau_0 = \cos \frac{\tau}{2} \cos \eta$. Therefore,

$$\omega \left(\frac{1}{2}\varphi, \eta \right) \Big|_{n=3} = \frac{\varphi}{2} - \frac{\pi}{2} + \kappa. \quad (19)$$

Collecting results for all six triangles, we reproduce Eq. (5.4) of [3] (see also in [4]),

$$\Omega^{(3;3)} = \Omega^{(3)} = \psi_{12} + \psi_{23} + \psi_{31} - \pi. \quad (20)$$

4.2. $n = 2$ ($\varepsilon = 1$)

In this case, the function F_1 reduces to

$$\begin{aligned} F_1 \left(1, 1, 1; \frac{3}{2} \middle| x, y \right) \\ = \frac{1}{x-y} \left[\frac{\sqrt{x} \arcsin \sqrt{x}}{\sqrt{1-x}} - \frac{\sqrt{y} \arcsin \sqrt{y}}{\sqrt{1-y}} \right]. \end{aligned}$$

In this way, we get

$$F_1 \left(1, 1, 1; \frac{3}{2} \middle| \sin^2 \frac{\varphi}{2}, \sin^2 \frac{\tau}{2} \right) = \frac{\varphi - \tau \sin \eta}{\sin \varphi \cos^2 \tau_0}$$

and, therefore,

$$\omega \left(\frac{1}{2}\varphi, \eta \right) \Big|_{n=2} = \frac{1}{4}\tau \sin \eta. \quad (21)$$

Collecting results for all six triangles, we get

$$\Omega^{(3;2)} = \frac{1}{2} (\tau_{12} \sin \eta_{12} + \tau_{23} \sin \eta_{23} + \tau_{13} \sin \eta_{13}).$$

Recalling that the two-point integral in two dimensions is proportional to $\tau / \sin \tau$ (see Eq. (4.3) of Ref. [3]), we see that the three-point integral (with $n = 2$) is a combination of three two-point integrals, with coefficients proportional to $\sin \tau_{jl} \sin \eta_{jl}$ (cf. Eq. (10) of Ref. [4]).

4.3. $n = 5$ ($\varepsilon = -\frac{1}{2}$)

In this case, we obtain

$$\begin{aligned} \omega \left(\frac{1}{2}\varphi, \eta \right) \Big|_{n=5} &= \frac{\pi}{2} - \frac{\varphi}{2} - \kappa \\ &+ \frac{1}{2} \tan \eta \ln \left(\frac{1 + \sin \frac{\tau}{2}}{1 - \sin \frac{\tau}{2}} \right). \end{aligned}$$

Collecting results for all six triangles, we get

$$\begin{aligned} \Omega^{(3;5)} &= -(\psi_{12} + \psi_{23} + \psi_{31} - \pi) \\ &+ \tan \eta_{12} \ln \left(\frac{m_1 + m_2 + \sqrt{k_{12}^2}}{m_1 + m_2 - \sqrt{k_{12}^2}} \right) \\ &+ \tan \eta_{23} \ln \left(\frac{m_2 + m_3 + \sqrt{k_{23}^2}}{m_2 + m_3 - \sqrt{k_{23}^2}} \right) \\ &+ \tan \eta_{13} \ln \left(\frac{m_1 + m_3 + \sqrt{k_{13}^2}}{m_1 + m_3 - \sqrt{k_{13}^2}} \right). \end{aligned}$$

In other words, the five-dimensional three-point integral can be expressed in terms of the three-dimensional three- and two-point integrals (see Eqs. (5.4) and (4.6) of [3]), in agreement with Eq. (17).

4.4. $n = 4$ ($\varepsilon \rightarrow 0$)

In this case, we need to expand the F_1 function up to the term linear in ε (it is easy to see that the ε^0 term cancels the $\frac{\varphi}{2}$ contribution). The result can be presented in terms of Clausen function, see Eq. (5.21) of [3]. Collecting three contributions of this type, we get $6 \times 3 = 18$ Clausen functions that can be analytically continued in terms of 12 dilogarithms [18]. In Ref. [6] the result is presented in terms of 15 Clausen functions.

5. ANALYTIC CONTINUATION

In the integral occurring in Eq. (9), let us substitute $z \Rightarrow e^{2i\phi}$, so that $\cos^2 \phi \Rightarrow \frac{(1+z)^2}{4z}$ and

$$1 + \frac{\tan^2 \eta}{\cos^2 \phi} \Rightarrow \frac{(z + \rho)(z + 1/\rho)}{(z + 1)^2}, \quad (22)$$

with

$$\rho \equiv \frac{1 - \sin \eta}{1 + \sin \eta}. \quad (23)$$

In this way, we get

$$\begin{aligned} &\int_0^{\varphi/2} d\phi \left(1 + \frac{\tan^2 \eta}{\cos^2 \phi} \right)^{-\varepsilon} \\ &\Rightarrow \frac{i}{2} \int_{z_0}^1 \frac{dz}{z} \left[\frac{(z + \rho)(z + 1/\rho)}{(z + 1)^2} \right]^{-\varepsilon}, \quad (24) \end{aligned}$$

with $z_0 \leftrightarrow e^{i\varphi}$. Expanding in ε , we get

$$Q_j \equiv \int_{z_0}^1 \frac{dz}{z} \ln^j \left[\frac{(z+\rho)(z+1/\rho)}{(z+1)^2} \right]. \quad (25)$$

The first term,

$$Q_1 = \text{Li}_2(-z_0\rho) + \text{Li}_2(-z_0/\rho) - 2\text{Li}_2(-z_0) + \frac{1}{2}\ln^2\rho, \quad (26)$$

yields the known result [18] for the three-point function in four dimensions. The r.h.s. of Eq. (26) can also be presented as

$$2\text{Li}_2(z_0) - \text{Li}_2\left(\frac{\rho+z_0}{\rho+z_0^{-1}}\right) - \text{Li}_2\left(z_0^2 \frac{\rho+z_0^{-1}}{\rho+z_0}\right) + \frac{1}{2}\ln^2\rho - \frac{1}{2}\ln^2\left[\frac{z_0\rho(\rho+z_0^{-1})}{\rho+z_0}\right], \quad (27)$$

in agreement with Eq. (5.17) of Ref. [3].

The second term, Q_2 , gives the ε term of the three-point function. For $j=2$, the integral (25) can be evaluated in terms of polylogarithms,

$$Q_2 = Q_2^{(1)}(z_0, \rho) \ln\rho + Q_2^{(2)}(z_0, \rho), \quad (28)$$

$$\begin{aligned} Q_2^{(1)} &= 2\text{Li}_2\left(\frac{1-\rho}{1+z_0\rho}\right) + 2\text{Li}_2\left(\frac{z_0(\rho-1)}{1+z_0\rho}\right) \\ &\quad - 2\text{Li}_2\left(\frac{\rho-1}{z_0+\rho}\right) - 2\text{Li}_2\left(\frac{z_0(1-\rho)}{z_0+\rho}\right) \\ &\quad - \text{Li}_2\left(\frac{1-\rho^2}{1+z_0\rho}\right) - \text{Li}_2\left(\frac{z_0(\rho^2-1)}{\rho(1+z_0\rho)}\right) \\ &\quad + \text{Li}_2\left(\frac{\rho^2-1}{\rho(z_0+\rho)}\right) + \text{Li}_2\left(\frac{z_0(1-\rho^2)}{z_0+\rho}\right), \\ Q_2^{(2)} &= 4\text{S}_{1,2}\left(\frac{1-\rho}{1+z_0\rho}\right) - 4\text{S}_{1,2}\left(\frac{z_0(\rho-1)}{1+z_0\rho}\right) \\ &\quad + 4\text{S}_{1,2}\left(\frac{\rho-1}{z_0+\rho}\right) - 4\text{S}_{1,2}\left(\frac{z_0(1-\rho)}{z_0+\rho}\right) \\ &\quad - \text{S}_{1,2}\left(\frac{1-\rho^2}{1+z_0\rho}\right) + \text{S}_{1,2}\left(\frac{z_0(\rho^2-1)}{\rho(1+z_0\rho)}\right) \\ &\quad - \text{S}_{1,2}\left(\frac{\rho^2-1}{\rho(z_0+\rho)}\right) + \text{S}_{1,2}\left(\frac{z_0(1-\rho^2)}{z_0+\rho}\right). \end{aligned}$$

Note that the arguments of Nielsen polylogarithms $\text{S}_{1,2}$ are the same as the arguments of Li_2 .

Furthermore,

$$\begin{aligned} \frac{\partial}{\partial\rho} Q_2^{(2)}(z_0, \rho) &= -\ln\rho \frac{\partial}{\partial\rho} Q_2^{(1)}(z_0, \rho), \\ \rho \frac{\partial}{\partial\rho} Q_2^{(1)}(z_0, \rho) &= Q_2^{(1)}(z_0, \rho). \end{aligned}$$

Another useful representation for $Q_2^{(1)}$ reads

$$Q_2^{(1)} = 2\text{Li}_2\left(-\frac{\rho+z_0}{1+\rho z_0}\right) - 2\text{Li}_2\left(-\frac{1+\rho z_0}{\rho+z_0}\right) + 2\ln\left[\frac{\rho}{(\rho+1)^2}\right] \ln\left(\frac{1+\rho z_0}{\rho+z_0}\right). \quad (29)$$

The occurring $\text{S}_{1,2}$ functions can be presented in terms of trilogarithms Li_3 . This result corresponds to Eq. (82) of Ref. [13]. We note that the first calculation of the ε -term of the one-loop three-point function was given in Ref. [19] (see also Ref. [20] for the off-shell massless case).

Eq. (25) shows that all higher terms of the ε -expansion of the one-loop three-point function can be expressed in terms of one-fold integrals of the products of logarithms of three linear arguments. (For some specific configurations, the ε^2 terms were studied in Ref. [21].) The considered representations may be useful to understand the types of generalized functions needed to describe the analytic structure of the results for higher terms of the ε -expansion.

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